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## LETTER TO THE EDITOR

## $q$-deformations of the $O(3)$ symmetric spin-1 Heisenberg chain

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#### Abstract

We present the general expression for the spin-1 Heisenberg chain invariant under the $U_{q}[\mathrm{SO}(3)]$ quantum algebra. Several physical and mathematical implications are discussed.


Recently there has been a considerable interest in the properties of the one-dimensional $\mathrm{O}(3)$ symmetric spin-1 Heisenberg chain defined by the Hamiltonian (Affleck et al 1988, Papanicolaou 1988, Barber and Batchelor 1989b and references therein):

$$
\begin{align*}
& H=\alpha \sum_{k=1}^{n} O_{k}(a, b) \\
& O_{k}(a, b)=a\left(\boldsymbol{S}_{k} \cdot \boldsymbol{S}_{k+1}\right)+b\left(\boldsymbol{S}_{k} \cdot \boldsymbol{S}_{k+1}\right)^{2} \tag{1}
\end{align*}
$$

where $\alpha=+1(-1)$ corresponds to the antiferromagnetic (ferromagnetic) chain ( $a \geqslant 0$ ). The eigenvalues of the matrix $O_{k}$ are

$$
\begin{equation*}
E_{0}=-2 a+4 b \quad E_{1}=-a+b \quad E_{2}=a+b . \tag{2}
\end{equation*}
$$

$E_{J}$ is the eigenvalue corresponding to total angular momentum $J$ (where $S_{k}+S_{k+1}=J$ ). Exact results have been obtained when two of the three eigenvalues coincide. We thus know that for $a=b=\alpha=1$ (Sutherland 1975, de Vega 1989) the system is massless with a central charge $c=2$ of the Virasoro algebra. This point is $\operatorname{SU}(3)$ symmetric ( $E_{2}=E_{0}$ ) and corresponds to the $3 \times 3=6+\overline{3}$ branching rules. Furthermore, the matrices

$$
\begin{equation*}
V_{k}=O_{k}(1,1)-1 \tag{3}
\end{equation*}
$$

satisfy the Hecke algebra (Jimbo 1986):

$$
\begin{align*}
& V_{k}^{2}=1 \quad\left[V_{k}, V_{k^{\prime}}\right]=0 \quad\left(\left|k-k^{\prime}\right| \geqslant 2\right)  \tag{4a}\\
& V_{k} V_{k+1} V_{k}=V_{k+1} V_{k} V_{k+1} . \tag{4b}
\end{align*}
$$

The point $a=0, b=\alpha=1\left(E_{2}=E_{1}\right)$ also has $\operatorname{SU}(3)$ invariance, corresponding to the $3 \times \overline{3}=1+8$ branching rules. The matrices

$$
\begin{equation*}
U_{k}=0_{k}(0,1)-1 \tag{5}
\end{equation*}
$$

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satisfy the Temperley-Lieb algebra (Barber and Batchelor 1989a)

$$
\begin{align*}
& U_{k}^{2}=\beta U_{k} \quad\left[U_{k}, U_{k^{\prime}}\right]=0 \quad\left(\left|k-k^{\prime}\right| \geqslant 2\right)  \tag{6a}\\
& U_{k} U_{k+1} U_{k}=U_{k} \tag{6b}
\end{align*}
$$

with $\beta=3$. We remind the reader that according to the lore derived from the spin- $\frac{1}{2}$ Heisenberg chain, a system has a second-order phase transition if $-2 \leqslant \beta \leqslant 2$ and a first-order transition otherwise. The fact that the Hamiltonian with $O_{k}(0,1)$ describes a massive phase was confirmed by the inversion relation calculations of Klümper (1989a, b). The case $\alpha=a=1, b=1 / 3\left(E_{1}=E_{0}\right)$ was solved by Affleck et al (1988), who obtained again a massive phase. Finally the case $a=-b=1$ (no two $E_{J} \mathrm{~s}$ have the same value) corresponds to the $O(3)$ symmetric Zamolodchikov-Fateev (1980) chain. Here one obtains a massless phase with a central charge $c=3 / 2$ for $\alpha=1$ (Alcaraz and Martins 1989a and references therein) and $c=1$ for $\alpha=-1$ (Alcaraz and Martins 1989b, Baranowski and Rittenberg 1990).

In the present letter we consider the $q$-deformation of the Hamiltonian (1). We first define the $U_{q}[S U(2)]$ quantum algebra (see, e.g., Jimbo 1985):

$$
\begin{equation*}
\left[\bar{S}^{2}, \bar{S}^{ \pm}\right]= \pm \bar{S}^{ \pm} \quad\left[\bar{S}^{+}, \bar{S}^{-}\right]=\left[2 \bar{S}^{2}\right]_{q} \tag{7}
\end{equation*}
$$

where

$$
\begin{equation*}
[x]_{q}=\left(q^{x}-q^{-x}\right)\left(q-q^{-1}\right)^{-1} \tag{8}
\end{equation*}
$$

For the three-dimensional representation $(J=1)$ we have

$$
\begin{equation*}
\bar{S}^{ \pm}=\sqrt{\frac{[2]_{q}}{2}} S^{ \pm} \quad \bar{S}^{z}=S^{z} \tag{9}
\end{equation*}
$$

where the $S^{ \pm}, S^{z}$ matrices are the same as those used in (1) ( $\left.S^{ \pm}=S^{x} \pm \mathrm{i} S^{y}\right)$. Using the Casimir operator

$$
\begin{equation*}
C_{2}=\bar{S}^{-} \bar{S}^{+}+\left(\left[\bar{S}^{z}+\frac{1}{2}\right]_{q}\right)^{2} \tag{10}
\end{equation*}
$$

one can construct $U_{q}[S U[2)]$ invariant quantities. We consider the tensor product (co-multiplication) of two $J=1$ representations:

$$
\begin{align*}
& \bar{S}^{ \pm}=\bar{S}_{k}^{ \pm} q^{\bar{S}_{\bar{L}+1}}+q^{-\bar{S}_{\bar{k}}} \bar{S}_{k+1}^{ \pm}=\sqrt{\frac{[2]_{q}}{2}}\left(S_{k}^{ \pm} q^{S_{k+1}^{z}}+q^{-S_{k}^{\bar{E}}} S_{k+1}^{ \pm}\right) . \\
& q^{\bar{S}^{z}}=q^{S_{k}^{z}} q^{S_{k+1}^{z}} . \tag{11}
\end{align*}
$$

Using (11) we can compute $C_{2}$ and $\left(C_{2}\right)^{2}$ in order to derive the $q$-deformation of $O_{k}(a, b)$, which we denote by $O_{k}(a, b ; q)$. We obtain

$$
\begin{align*}
O_{k}(a, b ; q)= & a\left(S_{k} \cdot S_{k+1}\right)+b\left(S_{k} \cdot S_{k+1}\right)^{2} \\
& +\left(\sinh ^{2} \lambda\right)\left[2 a\left(S_{k}^{z}\right)^{2}+2 a\left(S_{k+1}^{z}\right)^{2}+(a-b)\left(S_{k}^{z} S_{k+1}^{z}-\left(S_{k}^{z}\right)^{2}\left(S_{k+1}^{z}\right)^{2}\right)\right] \\
& +\frac{1}{2}(a+b)(\sinh \lambda)\left[\left(S_{k}^{x} S_{k+1}^{x}+S_{k}^{y} S_{k+1}^{y}\right)\left(S_{k+1}^{z}-S_{k}^{z}\right)+\mathrm{HC}\right] \\
& +2(b-a)\left(\sinh ^{2} \frac{\lambda}{2}\right)\left[\left(S_{k}^{x} S_{k+1}^{x}+S_{k}^{y} S_{k+1}^{y}\right) S_{k}^{z} S_{k+1}^{z}+\mathrm{HC}\right] \\
& +(\sinh 2 \lambda)\left[a\left(S_{k+1}^{z}-S_{k}^{z}\right)+\frac{1}{2}(a+b) S_{k}^{z} S_{k+1}^{z}\left(S_{k+1}^{z}-S_{k}^{z}\right)\right] \tag{12}
\end{align*}
$$

where $q=\mathrm{e}^{\lambda}$. The eigenvalues of $O_{k}(a, b ; q)$, which are $q$-dependent, are

$$
\begin{array}{ll}
E_{0}(q)=-2 a+b\left(q+q^{-1}\right)^{2} & E_{1}(q)=-a+b \\
E_{2}(q)=a\left(q^{2}+q^{-2}-1\right)+b . & \tag{13}
\end{array}
$$

For $q=1$ we recover the values given in (2). We are now about to have some surprises. If you take $a=b=1$ we have $E_{2}(q)=E_{0}(q)$ as in the $q=1$ case. This result is unexpected since the $U_{q}[S O(3)]$ should break the $S U(3)$ multiplet structure. At the same time, the $U_{q}[S U(3)]$ invariant Hamiltonian obtained by taking the $3 \times 3$ representations is given by (de Vega 1989 and references therein)

$$
\begin{equation*}
O_{k}^{3 \times 3}=\sum_{r s} T_{k}^{r s} T_{k+1}^{r s}+\sinh \lambda \sum_{r, s} \operatorname{sgn}(r-s) T_{k}^{r r} T_{k+1}^{s s}+1 \tag{14}
\end{equation*}
$$

where the $3 \times 3$ matrix $T^{r s}$ has all its elements zero except the one in the $r$-row and $s$-column which is equal to one. This matrix has the eigenvalues

$$
\begin{equation*}
E_{\overline{3}}=1-\frac{\left(q+q^{-1}\right)}{2} \quad E_{6}=1+\frac{q+q^{-1}}{2} \tag{15}
\end{equation*}
$$

which are different from those given by (13) (except for $q=1$ ). This raises the question of whether our $a=b=1$ Hamiltonian corresponds to a new $\operatorname{SU}(3)$ deformation. (We should keep in mind that the decomposition $\mathrm{SU}(3) \supset \mathrm{SO}(3)$ as opposed to $\mathrm{SU}(3) \supset$ $S U(2) \otimes U(1)$ leaves only one element in the Cartan subalgebra instead of two, and thus the effect of the $\mathrm{SO}(3)$ deformation is unclear.) To answer this question, we have next computed the eigenvalues of the matrix

$$
\begin{equation*}
O_{k}(1,1 ; q)+\eta O_{k+1}(1,1 ; q) \tag{16}
\end{equation*}
$$

where $\eta$ is a parameter. If there is an $\mathrm{SU}(3)$ structure, the degeneracy of eigenvalues should be given by the branching rule

$$
\begin{equation*}
3 \times 3 \times 3=1+8_{1}+8_{2}+10 . \tag{17}
\end{equation*}
$$

The actual calculation gives, for any value of $\eta$, six different eigenvalues instead of four: a singlet, two triplets, two quintets and a decuplet. So the single remnant of the $\mathrm{SU}(3)$ structure is the decuplet. It is thus probable that the higher degeneracies so far observed will disappear when we consider a higher number of sites. Moreover, as opposed to the $O_{k}^{3 \times 3}$ defined by (14) which have the property that $O_{k}^{3 \times 3}-1$ satisfy a Hecke algebra (Jimbo 1986), one can prove that there is no value of $\xi$ for which

$$
\begin{equation*}
W_{k}=O_{k}(1,1 ; q)-\xi \tag{18}
\end{equation*}
$$

satisfy the relation ( $4 b$ ) and thus the model is probably not integrable. The phase structure of this model remains to be studied. In particular, it would be interesting to know whether there is a second-order phase transition when $q$ is a root of unity.

We now consider the case $a=0, b=1$. We notice again the relation $E_{2}(q)=E_{1}(q)$ as for $q=1$. We observe that the matrix

$$
\begin{equation*}
U_{k}=O_{k}(0,1 ; q)-1 \tag{19}
\end{equation*}
$$

has the following matrix elements:
$\left\langle m_{1}, m_{2}\right| U_{k}\left|m_{1}^{\prime}, m_{2}^{\prime}\right\rangle=\delta_{m_{1}+m_{2}, 0} \delta_{m_{1}^{\prime}+m_{2}^{\prime}, 0} q^{m_{1}+m_{i}^{\prime}}(-1)^{m_{1}-m_{1}^{\prime}} \quad(-S \leqslant m \leqslant S, S=1)$
and that the Temperley-Lieb algebra is satisfied with $\beta=[3]_{q}$. This result is interesting since by choosing $q=\mathrm{e}^{\mathrm{i} \phi}$ and $\phi \geqslant \pi / 6$, one obtains $\beta \leqslant 2$ and presumably a secondorder phase transition. One physical consequence of our result is that it includes a further integrable quantum spin chain which, via the Temperley-Lieb equivalence, should belong to the Potts universality class. What happens for $0<\phi<\pi / 6$ and
rational is an open question. A direct calculation of the $U_{q}[\mathrm{SU}(3)]$ invariant for the $3 \times \overline{3}$ product gives

$$
\begin{align*}
& O_{k}^{3 \times 3}=\sum_{r, s} T_{k}^{r s} T_{k+1}^{r s}+\left(q^{-2}-1\right) T_{k}^{22} T_{k+1}^{22}+\left(q^{2}-1\right) T_{k}^{33} T_{k+1}^{33}+\left(q^{-1}-1\right)\left(T_{k}^{12} T_{k+1}^{12}+T_{k}^{21} T_{k+1}^{21}\right) \\
&+(q-1)\left(T_{k}^{13} T_{k+1}^{13}+T_{k}^{31} T_{k+1}^{31}\right) \tag{21}
\end{align*}
$$

and one can easily check that $O_{k}^{3 \times \overline{3}}=O_{k}(0,1 ;-q)$. We have found no explanation for the fact that the $\operatorname{SU}(3)$ structure is maintained in the $\mathbf{3} \times \overline{\mathbf{3}}$ case and is not in the $\mathbf{3} \times \mathbf{3}$ case.

A remarkable feature of $O_{k}^{3 \times \overline{3}}$ is that it can be used to construct a Hamiltonian for a closed chain, which preserves translational invariance. (This is not possible for $O_{k}^{3 \times 3}$.) In the region of the second-order phase transition, one could determine by inspection of the finite-size scaling spectra the equivalent of the modular invariants with $U_{q}[\mathrm{SU}(3)]$ symmetry.

Equation (20) generalises to higher spins: for $S>1$, the matrices $U_{k}$ again satisfy the Temperley-Lieb algebra with $\beta=[n]_{q}, n=2 S+1$. This generalises a result obtained by Affleck (1989) and Batchelor and Barber (1989) for the undeformed case.

The condition $E_{1}(q)=E_{0}(q)$ which might allow the method of valence bond (Affleck et al 1988) to be applied is given by the line

$$
\begin{equation*}
\frac{a}{b}=\left(q+q^{-1}\right)^{2}-1 \tag{22}
\end{equation*}
$$

Finally taking $a=-b=1$ in (12), one obtains the bulk terms of the Zamolodchikov and Fateev (1980) model. The effect of the surface terms will be considered elsewhere (Pasquier and Saleur 1989, Mezincescu et al 1989).
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